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2.094 Finite Element Analysis of Solids and Fluids Spring 2008

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2.094 — Finite Element Analysis of Solids and Fluids	Fall '08
Lecture 8 - Convergence of displacement-based FEM	
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(A) Find

$$\boldsymbol{u} \in \mathbf{V}$$
 such that $a(\boldsymbol{u}, \boldsymbol{v}) = (\boldsymbol{f}, \boldsymbol{v}) \quad \forall \boldsymbol{v} \in \mathbf{V} \text{ (Mathematical model)}$ (8.1)

$$a(\boldsymbol{v}, \boldsymbol{v}) > 0 \quad \forall \boldsymbol{v} \in \mathbf{V}, \quad \boldsymbol{v} \neq \boldsymbol{0}.$$
 (8.2)

where (8.2) implies that structures are supported properly. E.g.



(B) F.E. Problem Find

 $\boldsymbol{u}_h \in \mathcal{V}_h$ such that $a(\boldsymbol{u}_h, \boldsymbol{v}_h) = (\boldsymbol{f}, \boldsymbol{v}_h) \quad \forall \boldsymbol{v}_h \in \mathcal{V}_h$ (8.3)

 $a(\boldsymbol{v}_h, \boldsymbol{v}_h) > 0 \quad \forall \boldsymbol{v}_h \in \mathcal{V}_h, \quad \boldsymbol{v}_h \neq 0$ (8.4)

Properties $\boldsymbol{e}_h = \boldsymbol{u} - \boldsymbol{u}_h$

(I)
$$a(\boldsymbol{e}_h, \boldsymbol{v}_h) = 0 \quad \forall \boldsymbol{v}_h \in \mathbf{V}_h$$
 (8.5)

$$(II) \ a(\boldsymbol{u}_h, \boldsymbol{u}_h) \le a(\boldsymbol{u}, \boldsymbol{u}) \tag{8.6}$$



(C) Assume $\operatorname{Mesh}\Big|_{h_1}$ "is contained in" $\operatorname{Mesh}\Big|_{h_2}$



e.g. $\operatorname{Mesh}\Big|_{h_1}$ not contained in $\operatorname{Mesh}\Big|_{h_2}$



We assume (C), but need another property (independent of (C))

(III)
$$a(\boldsymbol{e}_h, \boldsymbol{e}_h) \le a(\boldsymbol{u} - \boldsymbol{v}_h, \boldsymbol{u} - \boldsymbol{v}_h) \quad \forall \boldsymbol{v}_h \in \mathbf{V}_h$$

$$(8.7)$$

 \boldsymbol{u}_h minimizes! (Recall $\boldsymbol{e}_h = \boldsymbol{u} - \boldsymbol{u}_h$)

Proof: Pick $\boldsymbol{w}_h \in \mathbf{V}_h$.

$$a(\boldsymbol{e}_{h} + \boldsymbol{w}_{h}, \boldsymbol{e}_{h} + \boldsymbol{w}_{h}) = a(\boldsymbol{e}_{h}, \boldsymbol{e}_{h}) + 2a(\boldsymbol{e}_{h}, \boldsymbol{w}_{h})^{-0} + \underbrace{a(\boldsymbol{w}_{h}, \boldsymbol{w}_{h})}_{\geq 0}$$
(8.8)

Equality holds for $(\boldsymbol{w}_h = \boldsymbol{0})$

$$a(\boldsymbol{e}_h, \boldsymbol{e}_h) \le a(\boldsymbol{e}_h + \boldsymbol{w}_h, \boldsymbol{e}_h + \boldsymbol{w}_h) \tag{8.9}$$

$$=a(\boldsymbol{u}-\boldsymbol{u}_h+\boldsymbol{w}_h,\boldsymbol{u}-\boldsymbol{u}_h+\boldsymbol{w}_h)$$
(8.10)

Take $\boldsymbol{w}_h = \boldsymbol{u}_h - \boldsymbol{v}_h$.

 $a(\boldsymbol{e}_h, \boldsymbol{e}_h) \le a(\boldsymbol{u} - \boldsymbol{v}_h, \boldsymbol{u} - \boldsymbol{v}_h)$ (8.11)

Using property (III) and (C), we can say that we will converge monotonically, from below, to a(u, u):



Pascal triangle (2D)



(Ch. 4.3)

error in displacement
$$\sim C \cdot h^{k+1}$$
 (8.12)

(C is a constant determined by the exact solution, material property...)

error in stresses
$$\sim C \cdot h^k$$
 (8.13)

error in strain energy
$$\sim C \cdot h^{2k}$$
 (\leftarrow these C are different) (8.14)

Hence,

$$E - E_h = C \cdot h^{2k}$$
 (roughly equal to) (8.15)

By theory,

$$\log\left(E - E_h\right) = \log C + 2k\log h \tag{8.16}$$



By experiment, we can evaluate $\log(E - E_h)$ for different meshes and plot $\log(E - E_h)$ vs. $\log h$



We need to use graded meshes if we have high stress gradients.

Example Consider an almost incompressible material:

$$\epsilon_V = \text{vol. strain}$$
 (8.17)

or

 $\nabla \cdot \boldsymbol{v} \to \text{very small or zero}$ (8.18)

We can "see" difficulties:

 $p = -\kappa \epsilon_V \quad \kappa = \text{ bulk modulus}$ (8.19)

As the material becomes incompressible ($\nu = 0.3 \rightarrow 0.4999$)

$$\begin{cases} \kappa \to \infty \\ \epsilon_V \to 0 \end{cases} \qquad p \to \text{ finite number}$$

$$(8.20)$$

(Small error in ϵ_V results in huge error on pressure as $\kappa \to \infty$, the constant C in (8.15) can be very large \Rightarrow locking)